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(71) Applicant:
Sony International (Europe) GmbH
10785 Berlin (DE)

(72) Inventors:

 Goronzy, Silke,
 Sony Inter. (Europe) GmbH 70736 Fellbach (DE) Kompe, Ralf,
 Sony Inter. (Europe) GmbH 70736 Fellbach (DE)

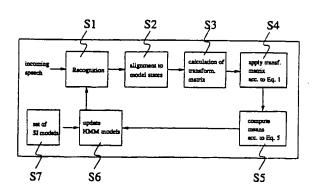
 Buchner, Peter,
 Sony Inter. (Europe) GmbH 70736 Fellbach (DE)

(74) Representative:
MÜLLER & HOFFMANN Patentanwälte
Innere Wiener Strasse 17
81667 München (DE)

(54) Maximum likelihood linear regression (MLLR) speaker adaptation using dynamic weighting

(57) According to the prior art Maximum Likelihood Linear Regression strategies have in common that the influence or weight of a new utterance remains the same throughout the whole adaptation process. According to the present invention, after a first very quick adaptation to a new speaker, new utterances are weighted less than all previous speaker specific utterances so that the sum of older utterances from a specific speaker have much more influence than a few new ones, if this speaker uses the system for a long time.

Fig. 1



Description

[0001] The present invention concerns a method to perform an unsupervised speaker adaptation for speech recognition systems that are using continous 5 density Hidden Markov Models (HMMs) with the Maximum Likelihood Linear Regression (MLLR) adaptation. State-of-the-art speech recognizers consist of a set of statistical distributions modeling the acoustic properties (encoded in feature vectors) of certain speech segments. As a simple example, one Gaussian distribution is taken for each phoneme. These distributions are attached to states. A stochastic model, usually continous density Hidden Markov Models, defines the propabilities for sequences of states and for acoustic properties given a state. Passing a state consumes one acoustic feature vector covering a frame of e. g. 10 ms of the speech signal. The stochastic parameters of such a recognizer are trained using a large amount of speech data either from a single speaker yielding a speaker dependent (SD) system or from many speakers yielding a speaker independent (SI) system.

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Nowadays most of the speech recognition [0003] systems using Hidden Markov Models to represent the different phonemes of a language are speaker independent. However, normally state-of-the-art speaker dependent systems yield much higher recognition rates than speaker independent systems. Therefore, speaker adaptation is a widely used method to increase the recognition rates of speaker independent systems. However, for many applications it is not feasible to gather enough data from a speaker to train the system. In case of a consumer device this might even not be wanted, since the device has to serve different users. To overcome this mismatch in recognition rates, speaker adaptation algorithms are widely used in order to achieve recognition rates that come close to speaker dependent systems, but only use a fraction of speaker dependent data compared to speaker dependent systems. These systems initially take speaker independent models and adapt them so that they better match to the new speakers acoustics by the use of the speech received from said speaker (adaptation data).

[0004] The basic principle of many speaker adaptation techniques is to modify the parameters of the Hidden Markov Models, e. g. those of the Gaussian densities modeling the acoustic features. In Maximum Likelihood Linear Regression adaptation a transformation matrix is calculated from the adaptation data and groups of model parameters, e. g. the mean vectors or the variance vectors etc., are multiplied with this transformation matrix (or n transformation matrices) to maximize the likelihood of the adaptation data.

[0005] Usually only the parameters of those Gaussian densities can be updated which corresponding phonemes have been observed in the adaptation data. In MLLR adaptation all Gaussian densities are clustered to build so-called regression classes. For each regres-

sion class a separate transformation matrix is calculated. Each time one or several phonemes from a specific regression class is/are observed in the adaptation data, a transformation matrix is calculated for this class and all Gaussian densities belonging to it are adapted. Thus, even those Gaussian densities for which the phonemes have not been observed in the adaptation data can be updated, what makes this approach faster than comparable ones, whereafter the next spoken utterance is analyzed with the updated model parameters and the adaptation can be performed in a next adaptation step.

[0006] As stated above, MLLR estimates linear transformations for groups of model parameters to maximize the likelihood of the adaptation data. Up to now, MLLR has been applied to the mean parameters and the Gaussian variances in mixture-Gaussian HMM-systems.

[0007] The above-described method according to the state of the art obtains good results with rather big amounts of adaptation data. If only very small amounts of adaptation data are available for each adaptation step, i. e. often only one utterance, which might e. g. be a single word, the calculation of the transformation matrices may partly be erroneous, because the adaptation statistics are estimated on non-representive data. Therefore, it is the object underlying the present invention to offer an improved method to perform an unsupervised speaker adaptation for continous density Hidden Markov Models using the Maximum Likelihood Linear Regression adaptation.

[0008] This object is solved according to independent claim 1, preferred embodiments are defined in dependent subclaims 2 to 9.

[0009] According to the inventive method a very fast adaptation can be achieved, since it is allowed to calculate the transformation matrix for each regression class reliable after a single (or a few) utterance(s), which correspond to only a few seconds of speech. Therewith, also an on-line adaptation is possible. After the calculation of the respective transformation matrix the group of parameters belonging to that regression class are updated and the next few seconds are then recognized using the HMMs that were modified in the previous step and so on. Therewith, a very fast adaptation to a new speaker can be performed.

[0010] The present invention will be better understood with the following detailed description of an exemplatory embodiment thereof taken in conjunction with Fig. 1 that shows a recognition and adaptation procedure including the dynamic weighting scheme and formulas (1) to (5).

[0011] The exemplatory embodiment of the present invention uses the mean parameters in mixture-Gaussian HMM-systems as group of model parameters that maximize the likelihood of the adaptation data. As mentioned above, the present invention is not limited thereto, but also the Gaussian variances or another

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group of model parameters can be used.

Fig. 1 shows the recognition and adaptation procedure including the dynamic weighting scheme according to the present invention.

[0012] In an initialization step all the mean vectors μ_i of the Gaussian densities are assigned to one of the regression classes r so that the means μ_{ir} are available as group of model parameters to maximize the likelihood of the adaptation data. The regression classes could be designed using a standard Vector Quantization algorithm, i. e. clustering feature vectors according to any numerical distance measure, but also the use of regression class trees or any other method is possible. The design and assignment of the regression classes r prior to recognition can also be performed dynamically depending on the amount of available adaptation data during the recognition process.

[0013] After the incoming speech has been recognized in a step S1, it is aligned to the model states in a step S2. Thereafter, the relevant statistics are extracted and used to calculate one transformation matrix W for each of the involved regression classes in step S3. New mean vectors $\hat{\mu}_{ir}$ are computed using a corresponding transformation matrix W_r by applying the following equation (1):

$$\hat{\mu}_{ir}^{k} = W_{r}^{*} \mu_{ir}^{k-1} \tag{1}$$

in a step S4 to calculate the estimated means $\hat{\mu}_{lr}^k$, where k is the current adaptation step and (k-1) the previous one, respectively. This updating operation of the means μ_{lr}^k in particular the computation of W_r is done according to known approaches of the prior art.

[0014] According to the prior art, these estimated means $\hat{\mu}_{ir}^k$ equal to the updated means μ_{ir}^k that are used in the modified HMM-models, as it is shown in equation (1a). W_r and thereby all $\hat{\mu}_{ir}^k$ from this regression class are estimated from the adaptation data observed for this regression class steps S6 and S7 are in the current adaptation step k. Thereafter, according to the prior art, steps S6 and S7 are directly performed wherein the HMM-models that are used without adaptation in a first adaptation step are adapted according to the following equation (1a)

$$\mu_{lr}^{k} = \hat{\mu}_{lr}^{k} \tag{1a}$$

[0015] As mentioned before, the procedure described so far works according to the procedure already known from the prior art. However, as also mentioned above, this method works only reliable with a rather big amount of adaptation data.

[0016] According to the present invention, on the other hand, the adapted mean according to equation (1) as it is calculated in step S4 is not directly used to modify the HMMs, but the adapted mean parameters are

modified in a step S5. Therefore, a weighted sum of the "old" and "new" mean is used to modify the HMM-models.

[0017] In step S5, therefore, the updated mean μ_{lr}^k is not only calculated as in equation (1a) above, where it directly corresponds to $\hat{\mu}_{lr}^k$, but is basically calculated as follows in equation (2):

$$\mu_{ir}^{k} = \alpha_{r} \hat{\mu}_{ir}^{k} + (1 - \alpha_{r}) \mu_{ir}^{k-1}$$
 (2)

where α_r is a first weighting factor for a respective regression class r. The index k starts with 1, μ_0^0 are the mean vectors of the speaker-independent system.

[0018] With a first fixed weighting factor $\alpha_r \sim 0,001$... 0,9 the new utterances represented by $\hat{\mu}_{ir}^k$ are weighted so that the data is adapted using a short term history having a α -dependent length. Therefore, the transformation matrices obtained on basis of small amounts of adaptation data that may be partly erroneous have a lower influence on the means used to modify the HMMs, but a fast adaptation is secured. Using this weighted sum allows a fast adaptation with only small amounts of adaptation data (e. g., 1 utterance) so that an on-line adaptation is possible.

In a preferred embodiment, the first weight-[0019] ing factor α_r is changed dynamically while the new speaker is using the system. A better performance can be gained when major changes to the HMMs are made when a new speaker starts using the system so that the HMMs better match his acoustics to have very quickly a low failure rate. Later, the changes should become smaller and smaller so that new utterances of a speaker are less weighted than all previous utterances of this specific speaker so that the sum of older utterances from this specific speaker have much more influence than the newly spoken ones. Therefore, the number of frames that have been observed so far are taken into account to dynamically change the first weighting factor α_r as follows in equation (3):

$$\alpha_r^k = \frac{n_r^k}{\tau_r^{k-1} + n_r^k}.$$
 (3)

[0020] Therefore, $(1-\alpha_r^k)$ of equation (2) above is defined as follows in equation (4).

$$(1-\alpha_r^k) = \frac{\tau_r^{k-1}}{\tau_r^{k-1} + n_r^k},$$
 (4)

where n_r^k is the number of frames that were observed so far during adaptation step k, $0 < k \le \infty$, in regression class r and τ_r^k is a second weighting factor determining the initial influence of the speaker Independent models, which is determined heuristically. τ_r^k can also be a con-

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stant.

[0021] According to a further preferred embodiment it is possible to allow any additional utterances after a first adaptation procedure to do only a fine adaptation. Therefore, the adaptation according to equations (3) 5 and (4) will be weighted with the number of speech frames that have already been observed from a specific speaker so that the adaptation that was already done in the past is used with a bigger weight than the new utterances. To perform this, τ_r^k increases by n_r^k after each 10 adaptation step so that

$$\tau_r^k = \tau_r^{k-1} + n_r^k.$$

 $\tau_{\,r}^{\,0}\,\,$ is an initial value determined heuristically and may vary between several hundreds and several thousands (e. g. 100 - 10.000).

[0022] Therewith, taking all preferred embodiments into account, equation 2 above can be re-written as:

$$\mu_{ir}^{k} = \frac{\tau_{r}^{k-1} \mu_{ir}^{k-1} + n_{r}^{k} \hat{\mu}_{ir}^{k}}{\tau_{r}^{k-1} + n_{r}^{k}}.$$
 (5)

[0023] Using this weighting scheme, α_r^k and thus the influence of the most recent observed means decreases over time and the parameters will move towards the optimum for that speaker after major changes to the HMM-models have been made when a 30 new speaker starts using the system.

Claims

- Method to perform an unsupervised speaker adaptation for Continuous Density Hidden Markov Models using the Maximum Likelihood Linear Regression adaptation, characterized in that an adapted group of parameters (a^k) to maximize the likelihood of the adaptation data is a weighted sum of the previously adapted group of parameters (a^k) and the estimated group of parameters (â^k) according to the Maximum Likelihood Linear Regression.
- 2. Method according to claim 1, characterized in that the weighted sum is calculated as follows:

$$a^k = \alpha \cdot \hat{a}^k + (1 \cdot \alpha) \cdot a^{k-1}$$

wherein k is the actual adaptation step, a^k is the adapted group of parameters that maximizes the likelihood of the adaptation data, a^{k-1} is the adapted group of parameters that previously maximized the likelihood of the adaptation data, \hat{a}^k is the estimated group of parameters that is calculated with the Maximum Likelihood Linear regression and α is a first weighting factor.

- Method according to claim 2 or 3, characterized in that said first weighting factor (α) changes dynamically depending on the time a new specific speaker is using the system.
- Method according to claim 3, characterized in that said first weighting factor (α) decreases with the time said specific speaker uses the system.
- Method according to claim 4, characterized in that the first weighting factor (α) is calculated as follows:

$$\alpha^{k} = \frac{n^{k}}{\tau^{k-1} + n^{k}},$$

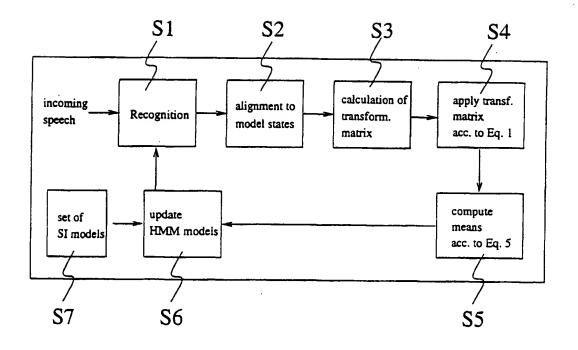
wherein n^k is the number of frames that were observed so far during adaptation step k and τ^{k-1} is a second weighting factor (τ) that is determined heuristically.

- 6. Method according to claim 5, characterized in that said second weighting factor (τ) is dependent on the number of speech frames that have already been observed from said specific speaker so that the adaptation already done has a bigger weight than newly spoken utterances.
- Method according to claim 5 or 6, characterized in that said second weighting factor (τ) increases by n^k after each adaptation step.
- 8. Method according to anyone of the preceeding claims, characterized in that said group of parameters (a^k) to maximize the likelihood of the adaptation data are the mean parameters (μ^k_{ir}, i: number of the respective Gaussian class, r: number of the respective regression class within the respective Gaussian class) in mixture-Gaussian HMM systems
- Method according to anyone of the preceeding claims, characterized in that said group of parameters (a^k) to maximize the likelihood of the adaptation data are the Gaussian variance parameters (Σ) in mixture-Gaussian HMM systems.

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Fig. 1





EUROPEAN SEARCH REPORT

Application Number EP 98 12 2791

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EUROPEAN SEARCH REPORT

Application Number EP 98 12 2791

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